

Click & Customize

Machine Tending Robots Ready to Work

Configure and receive a machine tending system in 2 weeks. From start to finish, let Vention do it all.



Guaranteed Productivity

Set your business up for longterm success by automating repetitive tasks.

Customization Delivered in 2 Weeks

Partner with a trusted expert and scalable ecosystem that adapts to your needs.

No Hassle

Let Vention build and deploy your custom solution, while you stay focused on your business.

Configure Your Machine Tending Solution

Jumpstart your design with our preassembled base and customize it for your needs.



Choose your base configuration

- Drawer system
- Angled part presenter

Choose your robot arm

- UR10e, UR20 or UR30 (Universal Robots)
- CRX-10iA/L or CRX-20iA/L (FANUC)
- GoFa10 or GoFa12 (ABB)

Choose your gripper

 More than 40 plug-and-play options from trusted brands like Schunk, OnRobot, and more.

Optionally add on other features

- Tower lights
- Area scanners
- Tool changers
- CNC door actuators
- Force torque sensors

Programming & deployment

- Native robot programming
- Vention's end-to-end service



Contact Vention to scope your system.

Technical Specifications

Base configuration

- Dimensions (without robot) of 1180mm(W) x 716mm(D) x 1038mm(H)
- Mobile with floor anchoring provisions for when in operation
- Access to internal components for ease of maintenance
- Additional mounting points inside the base for external components (air supply, auxiliary controls, etc.)
- Pre-wiring of inductive sensors and safety area scanners
- Includes ethernet cable passthroughs for CNC communication and 16 field wireables leads to use as needed for integration

• Universal Robots

UR10e - 12.5kg payload / 1300mm reach UR20 - 20kg payload / 1750mm reach UR30 - 30kg payload /1300mm reach

Robot arm

FANUC

CRX-10iA/L - 10kg payload / 1249mm reach CRX-20iA/L - 20kg payload / 1418mm reach

ABB

GoFa10 - 10kg payload / 1620mm reach GoFa12 - 12kg payload / 1370mm reach

Drawer version

Four double-sided drawers with lift to open release mechanism 2 inductive sensors per drawer to detect 4 drawer states Available part area per drawer 544mm x 710mm (21.38" x 27.95") Max part height 180mm (7.09") 100 kg (220 lbs) capacity per drawer

Part locating

Part Presenter

Trays come in 3 standard sizes or can be customized to the part requirements Available part presenting area $818 \, \text{mm} \times 738 \, \text{mm} (32.20^{\circ} \times 29.10^{\circ})$

Grippers

- Electric two and three finger grippers
- Pneumatic two finger grippers
- Single or dual gripper configurations
- Vacuum grippers

Safety (optional)

Datalogic Laser Area Scanner

5.5m radius safety zoneMultiple zone monitoring270 degrees of detection per area scanner

• Full 360 degrees of detection around the base







The Vention Difference



Work with the only company with the One-Factory Hardware Ecosystem where you can seamlessly connect everything from machine tending and welding robots to workstations, carts, jigs, and fixtures. Enjoy the power of customization with Vention's velocity of deployment.

Complete Customization

Configure and adapt equipment to your operations, not the other way around

Fast Deployment, Fast ROI

Get to production value in a few weeks and achieve ROI without surprises

End-to-End Service

Stay focused on your business while our robot experts design and deploy your system

Customer Story

Spector & Co, a leading supplier of promotional products focused on delivering merchandise and creative solutions for impactful brand experiences, automates repetitive machine tending tasks with company's first robot.



Problem

Inefficiencies in using hard-to-find labor in repetitive, non-fulfilling machine tending jobs.

Solution

Robotic machine tending solution with UR10e collaborative robot.

Key Results

Increased capacity to 100 bottles per hour, enabled a more predictable production schedule, and reallocated operators to more ergonomic tasks.

Why Choose Vention

25+

Industries served

4,000+

Factories using Vention

18,000+

Machines in the field